Initial validation of a simple, nonbiological, mechanical ERCP training model for cannulation and stent placement

Few models are available for hands-on training in endoscopic retrograde cholangiopancreatography (ERCP). Moreover, the key aspect of learning ERCP properly is the acquisition of manual and visual skills [1,2]. Although performing ERCP procedures in human beings eventually leads to expertise, both experts and endoscopy societies strongly encourage that some of the key skills be acquired with the use of training models [3]. Herein, we show a simple ERCP model for training endoscopists in scope insertion, wheel handling, cannulation, and stent insertion. The model consists of a metal cage, which serves to hold synthetic elements that comprise a model of the upper gastrointestinal and pancreaticobiliary tracts (Fig. 1, Video 1). The esophagus, stomach, and duodenal sweep are constructed from a plastic tube (Fig. 2 a). The papillae are made of latex, and the bile ducts are made of plastic. The pancreaticobiliary tree can be attached to the cage at various levels of difficulty (Fig. 2 b).

The model was placed on a table, and ERCP was then performed by five trainees and by five endoscopists with and without ERCP experience (Video 1). An Olympus duodenoscope (TJF-Q180V; Olympus America, Center Valley, Pennsylvania, USA) was used. The endoscopists were filmed, observed, and guided by two ERCP experts (Fig. 3, Video 1). The endoscopists also filled out questionnaires on various aspects of the model, including endoscope handling, visual realism, usefulness, and performance. The model was useful for performing and training in the

Fig. 1 The endoscopic retrograde cholangiopancreatography (ERCP) trainer consists of a metal cage, which serves to hold synthetic elements that comprise a model of the upper gastrointestinal and pancreaticobiliary tracts.

Fig. 2 Synthetic pancreaticobiliary tree. a The esophagus, stomach, and duodenal sweep are constructed from a plastic tube. b The pancreaticobiliary tree can be attached to the cage at various levels of difficulty.

Fig. 3 a, b The endoscopists are filmed, observed, and guided by two experts in endoscopic retrograde cholangiopancreatography.

Fig. 4 Deployed metal stent. An advantage of this model is that it is possible to remove the stent and reuse the papilla several times to practice stent placement and other therapeutic interventions.

Video 1

We validated this model for scope and wheel handling as well as cannulation, stent placement, stone extraction, brushing, and balloon dilation.

A simple, mechanical endoscopic retrograde cholangiopancreatography (ERCP) training model.
following steps: (i) introducing and positioning the scope, (ii) handling the wheels and elevator, (iii) positioning and targeting the papilla, (iv) cannulating the bile ducts, and (v) inserting plastic and metal stents (Fig. 4, Video 1).

In summary, this model appears novel and useful for various reasons. First, it can be used in any endoscopy unit. Second, there is no need to buy or use special endoscopes because the model is nonbiological and does not contain any tissue. Thus, the endoscope may be cleansed during standard reprocessing. In contrast, biological endoscope may be cleansed during standar reprocessing. In contrast, biological endoscopy requires a specific cleaning protocol.

Acknowledgments
The ERCP trainer was provided to our department for testing and training at no cost by Cook Medical, Winston-Salem, North Carolina, USA. The ERCP model was developed by Ivo Boškoski, MD, and Guido Costamagna, MD. Klaus Mönkemüller, MD, PhD, FASGE, is the 2014 recipient of an American Society of Gastrointestinal Endoscopy (ASGE) Endoscopic Research Award and has received honoraria from Cook Medical for lectures and hands-on training sessions given at Digestive Disease Week, which in 2015 was held in Washington, DC, USA. Ivan Jovanovic, MD, PhD, FASGE (a 2015 Fulbright Scholar) and Marco Aurelio D’Assunção, MD, are visiting professors at the University of Alabama at Birmingham, Alabama, USA. This work was done in part during their stay at the Basil I. Hirschowitz Endoscopic Center of Excellence of the University of Alabama at Birmingham.

Competing interests: None

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DOI http://dx.doi.org/10.1055/s-0034-1393389
Endoscopy 2015; 47: E585–E586
© Georg Thieme Verlag KG
Stuttgart · New York
ISSN 0013-726X

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Jovanovic Ivan et al. A simple, nonbiological, mechanical ERCP training model... Endoscopy 2015; 47: E585–E586